# Invariant Nonholonomic Riemannian Structures on Three-Dimensional Lie Groups

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#### Introduction

# Nonholonomic Riemannian manifold $(M, g, \mathcal{D})$

Model for motion of free particle

- moving in configuration space M with kinetic energy  $L=\frac{1}{2}g(\cdot,\cdot)$
- ullet constrained to move in "admissible directions"  ${\cal D}$

Invariant structures on Lie groups are of the most interest

#### Objective

- classify all left-invariant structures on 3D Lie groups
- characterise equivalence classes in terms of scalar invariants

For this talk: restrict to the unimodular Lie groups

DI Barrett, R Biggs, CC Remsing, O Rossi: Invariant nonholonomic Riemannian structures on three-dimensional Lie groups, *J. Geom. Mech.* **8**(2016), 139–167

#### Outline

- 1 Invariant nonholonomic Riemannian manifolds
  - Nonholonomic isometries
  - Curvature
- 2 3D simply connected unimodular Lie groups
- Classification of 3D structures
  - Case 1:  $\vartheta = 0$
  - Case 2:  $\vartheta > 0$

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# Invariant nonholonomic Riemannian manifold (G, g, D)

#### Ingredients

- (G, g) is an *n*-dim Riemannian Lie group (g is left invariant)
- ullet  ${\cal D}$  is a nonintegrable, left-invariant, rank r distribution on G

#### Assumption

ullet  $\mathcal{D}$  is completely nonholonomic: if

$$\mathcal{D}^1 = \mathcal{D}, \qquad \mathcal{D}^{i+1} = \mathcal{D}^i + [\mathcal{D}^i, \mathcal{D}^i], \ i \ge 1$$

then there exists  $N \ge 2$  such that  $\mathcal{D}^N = TG$ 

#### Chow-Rashevskii theorem

if  $\mathcal D$  is completely nonholonomic, then any two points in G can be joined by an integral curve of  $\mathcal D$ 

# Orthogonal decomposition $T\mathsf{G} = \mathcal{D} \oplus \mathcal{D}^{\perp}$

• projectors  $\mathscr{P}: \mathsf{TG} \to \mathcal{D}$  and  $\mathscr{Q}: \mathsf{TG} \to \mathcal{D}^{\perp}$ 

# Nonholonomic geodesics and the nonholonomic connection

#### D'Alembert's Principle

Let  $\widetilde{\nabla}$  be the Levi-Civita connection of  $(\mathsf{G},g)$ . An integral curve  $\gamma$  of  $\mathcal D$  is called a nonholonomic geodesic of  $(\mathsf{G},g,\mathcal D)$  if

$$\widetilde{
abla}_{\dot{\gamma}(t)}\dot{\gamma}(t)\in\mathcal{D}_{\gamma(t)}^{\perp}$$
 for all  $t$ 

Equivalently:  $\mathscr{P}(\widetilde{\nabla}_{\dot{\gamma}(t)}\dot{\gamma}(t))=0$  for every t

# NH connection $\nabla: \Gamma(\mathcal{D}) \times \Gamma(\mathcal{D}) \to \Gamma(\mathcal{D})$

$$\nabla_X Y = \mathscr{P}(\widetilde{\nabla}_X Y), \qquad X, Y \in \Gamma(\mathcal{D})$$

- depends only on  $(\mathcal{D}, g|_{\mathcal{D}})$  and the complement  $\mathcal{D}^{\perp}$
- integral curve  $\gamma$  of  ${\cal D}$  is a NH geodesic  $\iff \nabla_{\dot{\gamma}}\dot{\gamma}\equiv 0$

#### Nonholonomic isometries

## NH-isometry between $(G, g, \mathcal{D})$ and $(G', g', \mathcal{D}')$

diffeomorphism  $\phi: G \to G'$  such that

$$\phi_*\mathcal{D}=\mathcal{D}', \qquad \phi_*\mathcal{D}^\perp={\mathcal{D}'}^\perp \qquad \text{and} \qquad \left. \mathbf{g} \right|_{\mathcal{D}}=\left. \phi^*\mathbf{g}' \right|_{\mathcal{D}'}$$

Nonholonomic isometries preserve:

- the nonholonomic connection:  $\nabla = \phi^* \nabla'$
- nonholonomic geodesics
- projections:  $\phi_* \mathscr{P}(X) = \mathscr{P}'(\phi_* X)$  for every  $X \in \Gamma(TM)$

#### Curvature

- ullet  $\nabla$  is not a vector bundle connection on  ${\cal D}$
- usual curvature tensor  $(X,Y)\mapsto [\nabla_X,\nabla_Y]-\nabla_{[X,Y]}$  not defined

# Schouten curvature tensor $K:\Gamma(\mathcal{D}) imes\Gamma(\mathcal{D}) imes\Gamma(\mathcal{D}) o\Gamma(\mathcal{D})$

$$K(X,Y)Z = [\nabla_X, \nabla_Y]Z - \nabla_{\mathscr{P}([X,Y])}Z - \mathscr{P}([\mathscr{Q}([X,Y]),Z])$$

Associated (0, 4)-tensor

$$\widehat{K}(W,X,Y,Z)=g(K(W,X)Y,Z)$$

- $\widehat{K}(X,X,Y,Z)=0$
- $\widehat{K}(W, X, Y, Z) + \widehat{K}(X, Y, W, Z) + \widehat{K}(Y, W, X, Z) = 0$

# Decompose $\widehat{K}$

- $\widehat{R} =$  component of  $\widehat{K}$  that is skew-symmetric in last two args
- $\widehat{C} = \widehat{K} \widehat{R}$

 $(\hat{R}$  behaves like Riemannian curvature tensor)

#### Ricci-like curvatures

#### Ricci tensor Ric : $\mathcal{D} \times \mathcal{D} \to \mathbb{R}$

$$Ric(X, Y) = \sum_{a=1}^{r} \widehat{R}(X_a, X, Y, X_a)$$

- $(X_a)_{a=1}^r$  is an orthonormal frame for  $\mathcal{D}$
- Scal =  $\sum_{a=1}^{r} \text{Ric}(X_a, X_a)$  is the scalar curvature

## Ricci-type tensors $A_{sym}, A_{skew}: \mathcal{D} imes \mathcal{D} ightarrow \mathbb{R}$

$$A(X,Y) = \sum_{a=1}^{r} \widehat{C}(X_a, X, Y, X_a)$$

#### Decompose A

- $A_{sym} = \text{symmetric part of } A$
- $A_{skew} =$  skew-symmetric part of A

#### Nonholonomic Riemannian structures in 3D

#### Contact structure on G

We have  $\mathcal{D} = \ker \omega$ , where  $\omega$  is a 1-form on M such that

$$\omega \wedge d\omega \neq 0$$

• fixed up to sign by condition:

$$d\omega(Y_1, Y_2) = \pm 1,$$
  $(Y_1, Y_2)$  o.n. frame for  $\mathcal{D}$ 

• Reeb vector field  $Y_0 \in \Gamma(TG)$ :

$$i_{Y_0}\omega = 1$$
 and  $i_{Y_0}d\omega = 0$ 

#### Two natural cases

(1) 
$$Y_0 \in \Gamma(\mathcal{D}^{\perp})$$

(2) 
$$Y_0 \notin \Gamma(\mathcal{D}^{\perp})$$

## Scalar invariants in 3D

#### First invariant $\vartheta$

$$\vartheta = \|\mathscr{P}(Y_0)\|^2$$

•  $Y_0 \in \Gamma(\mathcal{D}^{\perp}) \iff \vartheta = 0$ 

#### Curvature invariants $\kappa$ , $\chi_1$ and $\chi_2$

$$\kappa = rac{1}{2}\operatorname{Scal} \qquad \chi_1 = \sqrt{-\det(g|_{\mathcal{D}}^{\sharp} \circ A_{\operatorname{sym}}^{\flat})} \qquad \chi_2 = \sqrt{\det(g|_{\mathcal{D}}^{\sharp} \circ A_{\operatorname{skew}}^{\flat})}$$

- $\bullet \ \widehat{R} \equiv 0 \quad \Longleftrightarrow \quad \kappa = 0$
- $\widehat{C} \equiv 0 \iff \chi_1 = \chi_2 = 0$

#### For unimodular groups:

•  $\chi_2 = 0$ 

structures are NH-isometric  $\implies$  their scalar invariants are equal

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# Bianchi–Behr classification of 3D unimodular Lie algebras

# Lie algebras and (simply connected) Lie groups

Lie algebra	Lie group	Name	Class
$\mathbb{R}^3$	$\mathbb{R}^3$	Abelian	Abelian
$\mathfrak{h}_3$	H <sub>3</sub>	Heisenberg	nilpotent
$\mathfrak{se}(1,1)$	SE(1,1)	semi-Euclidean	completely solvable
$\mathfrak{se}(2)$	$\widetilde{SE}(2)$	Euclidean	solvable
$\mathfrak{sl}(2,\mathbb{R})$	$\widetilde{SL}(2,\mathbb{R})$	special linear	semisimple
$\mathfrak{su}(2)$	SU(2)	special unitary	semisimple

# Left-invariant distributions on 3D groups

## Killing form

$$\mathcal{K}: \mathfrak{g} \times \mathfrak{g} \to \mathbb{R}, \qquad \mathcal{K}(U, V) = \operatorname{tr}[U, [V, \cdot]]$$

ullet  $\mathcal K$  is nondegenerate  $\iff \mathfrak g$  is semisimple

#### Completely nonholonomic left-invariant distributions on 3D groups

ullet no such distributions on  $\mathbb{R}^3$ 

#### Up to Lie group automorphism:

- exactly one distribution on  $H_3$ , SE(1,1), SE(2) and SU(2)
- exactly two distributions on  $SL(2,\mathbb{R})$ :

denote 
$$\widetilde{\mathsf{SL}}(2,\mathbb{R})_{hyp}$$
 if  $\mathcal{K}$  indefinite on  $\mathcal{D}$  "  $\widetilde{\mathsf{SL}}(2,\mathbb{R})_{ell}$  " " definite " "

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#### Case 1: $\vartheta = 0$

- $\bullet$  determined (up to equiv) by the sub-Riemannian structure (G,  $\mathcal{D}, \left. \mathbf{g} \right|_{\mathcal{D}})$
- invariant sub-Riemannian structures classified in

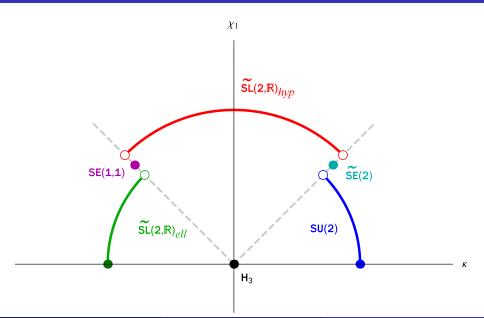
A Agrachev, D Barilari: Sub-Riemannian structures on 3D Lie groups, *J. Dyn. Control Syst.* **18**(2012), 21–44.

#### **Invariants**

- $\{\kappa, \chi_1\}$  form a complete set of invariants (in the unimodular case)
- can rescale structures so that

$$\kappa = \chi_1 = 0$$
 or  $\kappa^2 + \chi_1^2 = 1$ 

## Classification when $\vartheta = 0$



## Case 2: $\vartheta > 0$

## Canonical frame $(X_0, X_1, X_2)$

$$X_0 = \mathscr{Q}(Y_0)$$
  $X_1 = \frac{\mathscr{P}(Y_0)}{\|\mathscr{P}(Y_0)\|}$   $X_2$  unique unit vector s.t.  $d\omega(X_1, X_2) = 1$ 

- $\mathcal{D} = \operatorname{span}\{X_1, X_2\}, \ \mathcal{D}^{\perp} = \operatorname{span}\{X_0\}$
- canonical left-invariant frame (up to sign of  $X_0$ ,  $X_1$ ) on G

## Commutator relations (determine structure uniquely)

$$\begin{cases} [X_1, X_0] = & c_{10}^1 X_1 + c_{10}^2 X_2 \\ [X_2, X_0] = -c_{21}^1 X_0 + c_{20}^1 X_1 - c_{10}^1 X_2 \\ [X_2, X_1] = & X_0 + c_{21}^1 X_1 \end{cases} \qquad c_{10}^1, c_{10}^2, c_{20}^1, c_{21}^1 \in \mathbb{R},$$

#### Nonholonomic isometries

#### NH-isometries preserve the Lie group structure

$$(G,g,\mathcal{D})$$
 NH-isometric to  $(G',g',\mathcal{D}')$   $\Longrightarrow$   $\phi = L_{\phi(1)} \circ \phi'$ , where  $\phi'$  is a Lie group isomorphism

ullet hence NH-isometries preserve the Killing form  ${\cal K}$ 

#### Three new invariants $\varrho_0$ , $\varrho_1$ , $\varrho_2$

$$\varrho_i = -\frac{1}{2}\mathcal{K}(X_i, X_i), \qquad i = 0, 1, 2$$

## Classification

#### Approach

- ullet rescale frame so that artheta=1
- split into cases depending on structure constants
- determine group from commutator relations

# Example: $c_{10}^1 = c_{10}^2 = 0$

$$[X_1, X_0] = 0$$
  $[X_2, X_0] = -X_0 + c_{20}^1 X_1$   $[X_2, X_1] = X_0 + X_1$ 

- ullet implies  ${\cal K}$  is degenerate (i.e., G not semisimple)
  - (1)  $c_{20}^1 + 1 > 0 \implies \text{compl. solvable} \quad \text{hence on SE}(1,1)$
  - (2)  $c_{20}^1 + 1 = 0 \implies \text{nilpotent}$  " "  $H_3$
  - (3)  $c_{20}^1 + 1 < 0 \implies \text{solvable}$  " "  $\widetilde{\mathsf{SE}}(2)$
- for SE(1,1),  $\widetilde{SE}(2)$ :  $c_{20}^1$  is a parameter (i.e., family of structures)

#### Some of the results

$$\begin{aligned} & \text{H}_{3} & \begin{cases} [X_{1},X_{0}] = 0 \\ [X_{2},X_{0}] = -X_{0} - X_{1} \\ [X_{2},X_{1}] = X_{0} + X_{1} \end{cases} & \begin{cases} \varrho_{0} = 0 \\ \varrho_{1} = 0 \\ \varrho_{2} = 0 \end{cases} \\ \\ & \tilde{\text{SE}}(2) & \begin{cases} [X_{1},X_{0}] = -\sqrt{\alpha_{1}\alpha_{2}}\,X_{1} + \alpha_{1}X_{2} \\ [X_{2},X_{0}] = -X_{0} - (1+\alpha_{2})X_{1} + \sqrt{\alpha_{1}\alpha_{2}}\,X_{2} \end{cases} & \begin{cases} \varrho_{0} = \alpha_{1} \\ \varrho_{1} = \alpha_{2} \\ \varrho_{2} = \alpha_{2} \end{cases} \\ (\alpha_{1},\alpha_{2} \geq 0,\ \alpha_{1}^{2} + \alpha_{2}^{2} \neq 0) \end{cases} \\ & \text{SU}(2) & \begin{cases} [X_{1},X_{0}] = -\delta X_{0} + \alpha_{1}X_{2} \\ [X_{2},X_{0}] = -X_{0} - (1+\alpha_{2})X_{1} + \delta X_{2} \\ [X_{2},X_{1}] = X_{0} + X_{1} \end{cases} & \begin{cases} \varrho_{0} = \alpha_{1}(\alpha_{2} + 1) - \delta^{2} \\ \varrho_{1} = \alpha_{1} \\ \varrho_{2} = \alpha_{2} \end{cases} \\ (\alpha_{1},\alpha_{2} > 0,\ \delta \geq 0,\ \delta^{2} - \alpha_{1}\alpha_{2} < 0) \end{cases} \end{aligned}$$

#### Remarks

- $\{\vartheta, \varrho_0, \varrho_1, \varrho_2\}$  form a complete set of invariants
- (again, only for the unimodular case)

## Structures on 3D non-unimodular groups

On a fixed non-unimodular Lie group (except for  $G_{3.5}^1$ ), there exist at most two non-NH-isometric structures with the same invariants  $\vartheta$ ,  $\varrho_0$ ,  $\varrho_1$ ,  $\varrho_2$ 

- exception  $G_{3.5}^1$ : infinitely many  $(\varrho_0 = \varrho_1 = \varrho_2 = 0)$
- use  $\kappa$ ,  $\chi_1$  or  $\chi_2$  to form complete set of invariants