## RHODES UNIVERSITY DEPARTMENT of MATHEMATICS (Pure & Applied) CLASS TEST No. 2 : OCTOBER 2009 MATHEMATICS HONOURS

## GEOMETRIC CONTROL

AVAILABLE MARKS : 50 FULL MARKS : 50 DURATION : 1 HOUR

NB : All questions may be attempted.

## Question 1. (24 marks)

Let  $\Sigma = (\mathsf{G}, \Gamma)$  be a (right-invariant) control system with the understanding that the state space  $\mathsf{G}$  is a matrix Lie group and that the class  $\mathcal{U}$  of admissible controls consists of piecewise-constant controls.

- (a) Define the terms trajectory, attainable set (from  $g \in G$ ) and orbit (through  $g \in G$ ).
- (b) Explain what is meant by saying that a point (state)  $y \in G$  is normally attainable from  $x \in G$ .
- (c) State (but DO NOT prove) Krener's Theorem. Hence, prove that

 $\operatorname{Lie}(\Gamma) = \mathfrak{g} \iff \operatorname{int} \mathcal{A}(1) \neq \emptyset.$ 

(Here,  $\mathfrak{g}$  denotes the Lie algebra of  $\mathsf{G}$  and  $\mathcal{A}(1)$  denotes the attainable set from the identity  $1 \in \mathsf{G}$ .)

[9,3,12]

## Question 2. (26 marks)

Let  $\Sigma = (\mathsf{G}, \Gamma)$  be a (right-invariant) control system with the understanding that the state space  $\mathsf{G}$  is a matrix Lie group and that the class  $\mathcal{U}$  of admissible controls consists of piecewise-constant controls.

- (a) Explain what is meant by saying that  $\Sigma$  is *controllable*. Give necessary conditions for controllability.
- (b) State the following controllability tests
  - i. Group Test.
  - ii. Local Controllability Test.
  - iii. Closure Test.

Give *detailed* proofs for any two of these tests.

[4, 22]