

# Invariant Nonholonomic Riemannian Structures on Three-Dimensional Lie Groups

Dennis I. Barrett

Geometry, Graphs and Control (GGC) Research Group  
Department of Mathematics, Rhodes University  
Grahamstown, South Africa

Department of Mathematics  
The University of Ostrava  
8 July 2016

## Nonholonomic Riemannian structure $(M, g, \mathcal{D})$

Model for motion of free particle

- moving in configuration space  $M$
- kinetic energy  $L = \frac{1}{2}g(\cdot, \cdot)$
- constrained to move in “admissible directions”  $\mathcal{D}$

Invariant structures on Lie groups are of the most interest

## Objective

- classify all left-invariant structures on 3D Lie groups
- characterise equivalence classes in terms of scalar invariants

- 1 Nonholonomic Riemannian manifolds
  - Nonholonomic isometries
  - Curvature
- 2 Nonholonomic Riemannian structures in 3D
- 3 3D simply connected Lie groups
- 4 Classification of nonholonomic Riemannian structures in 3D
  - Case 1:  $\vartheta = 0$
  - Case 2:  $\vartheta > 0$
- 5 Flat nonholonomic Riemannian structures

- 1 Nonholonomic Riemannian manifolds
  - Nonholonomic isometries
  - Curvature
- 2 Nonholonomic Riemannian structures in 3D
- 3 3D simply connected Lie groups
- 4 Classification of nonholonomic Riemannian structures in 3D
  - Case 1:  $\vartheta = 0$
  - Case 2:  $\vartheta > 0$
- 5 Flat nonholonomic Riemannian structures

# Nonholonomic Riemannian manifold $(M, g, \mathcal{D})$

## Ingredients

- $(M, g)$  is an  $n$ -dim Riemannian manifold
- $\mathcal{D}$  is a nonintegrable, rank  $r$  distribution on  $M$

## Assumption

- $\mathcal{D}$  is **completely nonholonomic**: if

$$\mathcal{D}^1 = \mathcal{D}, \quad \mathcal{D}^{i+1} = \mathcal{D}^i + [\mathcal{D}^i, \mathcal{D}^i], \quad i \geq 1$$

then there exists  $N \geq 2$  such that  $\mathcal{D}^N = TM$

## Chow–Rashevskii theorem

if  $\mathcal{D}$  is completely nonholonomic, then any two points in  $M$   
can be joined by an integral curve of  $\mathcal{D}$

## Orthogonal decomposition $TM = \mathcal{D} \oplus \mathcal{D}^\perp$

- projectors  $\mathcal{P} : TM \rightarrow \mathcal{D}$  and  $\mathcal{Q} : TM \rightarrow \mathcal{D}^\perp$

## D'Alembert's Principle

Let  $\tilde{\nabla}$  be the Levi-Civita connection of  $(M, g)$ . An integral curve  $\gamma$  of  $\mathcal{D}$  is called a **nonholonomic geodesic** of  $(M, g, \mathcal{D})$  if

$$\tilde{\nabla}_{\dot{\gamma}(t)} \dot{\gamma}(t) \in \mathcal{D}_{\gamma(t)}^\perp \text{ for all } t$$

Equivalently:  $\mathcal{P}(\tilde{\nabla}_{\dot{\gamma}(t)} \dot{\gamma}(t)) = 0$  for every  $t$ .

- nonholonomic geodesics are the solutions of the **Chetaev equations**:

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{x}^i} - \frac{\partial L}{\partial x^i} = \sum_{a=1}^r \lambda_a \varphi^a, \quad i = 1, \dots, n$$

- $L = \frac{1}{2}g(\cdot, \cdot)$  is the kinetic energy Lagrangian
- $\varphi^a = \sum_{i=1}^n B_i^a dx^i$  span the annihilator  $\mathcal{D}^\circ = g^\flat(\mathcal{D}^\perp)$  of  $\mathcal{D}$
- $\lambda_a$  are Lagrange multipliers

# The nonholonomic connection

NH connection  $\nabla : \Gamma(\mathcal{D}) \times \Gamma(\mathcal{D}) \rightarrow \Gamma(\mathcal{D})$

$$\nabla_X Y = \mathcal{P}(\tilde{\nabla}_X Y), \quad X, Y \in \Gamma(\mathcal{D})$$

- affine connection
- parallel transport only along integral curves of  $\mathcal{D}$
- depends only on  $(\mathcal{D}, g|_{\mathcal{D}})$  and the complement  $\mathcal{D}^\perp$

## Characterisation

$\nabla$  is the unique connection  $\Gamma(\mathcal{D}) \times \Gamma(\mathcal{D}) \rightarrow \Gamma(\mathcal{D})$  such that

$$\nabla g|_{\mathcal{D}} \equiv 0 \quad \text{and} \quad \nabla_X Y - \nabla_Y X = \mathcal{P}([X, Y])$$

## Characterisation of nonholonomic geodesics

integral curve  $\gamma$  of  $\mathcal{D}$   
is a nonholonomic geodesic



$$\nabla_{\dot{\gamma}(t)} \dot{\gamma}(t) = 0 \text{ for every } t$$

## NH-isometry between $(M, g, \mathcal{D})$ and $(M', g', \mathcal{D}')$

diffeomorphism  $\phi : M \rightarrow M'$  such that

$$\phi_*\mathcal{D} = \mathcal{D}', \quad \phi_*\mathcal{D}^\perp = \mathcal{D}'^\perp \quad \text{and} \quad g|_{\mathcal{D}} = \phi^*g'|_{\mathcal{D}'}$$

### Properties

- preserves the nonholonomic connection:  $\nabla = \phi^*\nabla'$
- establishes a 1-to-1 correspondence between the nonholonomic geodesics of the two structures
- preserves the projectors:  $\phi_*\mathcal{P}(X) = \mathcal{P}'(\phi_*X)$  for every  $X \in \Gamma(TM)$

## Left-invariant nonholonomic Riemannian structure $(M, g, \mathcal{D})$

- $M = G$  is a Lie group
- left translations  $L_g : h \mapsto gh$  are NH-isometries



# Curvature

- $\nabla$  is not a vector bundle connection on  $\mathcal{D}$
- Riemannian curvature tensor not defined

Schouten curvature tensor  $K : \Gamma(\mathcal{D}) \times \Gamma(\mathcal{D}) \times \Gamma(\mathcal{D}) \rightarrow \Gamma(\mathcal{D})$

$$K(X, Y)Z = [\nabla_X, \nabla_Y]Z - \nabla_{\mathcal{P}([X, Y])}Z - \mathcal{P}([\mathcal{L}([X, Y]), Z])$$

Associated (0, 4)-tensor

$$\widehat{K}(W, X, Y, Z) = g(K(W, X)Y, Z)$$

- $\widehat{K}(X, X, Y, Z) = 0$
- $\widehat{K}(W, X, Y, Z) + \widehat{K}(X, Y, W, Z) + \widehat{K}(Y, W, X, Z) = 0$

Decompose  $\widehat{K}$

- $\widehat{R}$  = component of  $\widehat{K}$  that is skew-symmetric in last two args
- $\widehat{C} = \widehat{K} - \widehat{R}$

( $\widehat{R}$  behaves like Riemannian curvature tensor)

Ricci tensor  $\text{Ric} : \mathcal{D} \times \mathcal{D} \rightarrow \mathbb{R}$

$$\text{Ric}(X, Y) = \sum_{a=1}^r \widehat{R}(X_a, X, Y, X_a)$$

- $(X_a)_{a=1}^r$  is an orthonormal frame for  $\mathcal{D}$
- $\text{Scal} = \sum_{a=1}^r \text{Ric}(X_a, X_a)$  is the **scalar curvature**

Ricci-type tensors  $A_{sym}, A_{skew} : \mathcal{D} \times \mathcal{D} \rightarrow \mathbb{R}$

$$A(X, Y) = \sum_{a=1}^r \widehat{C}(X_a, X, Y, X_a)$$

Decompose  $A$

- $A_{sym}$  = symmetric part of  $A$
- $A_{skew}$  = skew-symmetric part of  $A$

- 1 Nonholonomic Riemannian manifolds
  - Nonholonomic isometries
  - Curvature
- 2 Nonholonomic Riemannian structures in 3D
- 3 3D simply connected Lie groups
- 4 Classification of nonholonomic Riemannian structures in 3D
  - Case 1:  $\vartheta = 0$
  - Case 2:  $\vartheta > 0$
- 5 Flat nonholonomic Riemannian structures

## Contact structure on $M$

We have  $\mathcal{D} = \ker \omega$ , where  $\omega$  is a 1-form on  $M$  such that

$$\omega \wedge d\omega \neq 0$$

- fixed up to sign by condition:

$$d\omega(Y_1, Y_2) = \pm 1, \quad (Y_1, Y_2) \text{ o.n. frame for } \mathcal{D}$$

- **Reeb vector field**  $Y_0 \in \Gamma(TM)$ :

$$i_{Y_0}\omega = 1 \quad \text{and} \quad i_{Y_0}d\omega = 0$$

## Two natural cases

$$(1) Y_0 \in \mathcal{D}^\perp \qquad (2) Y_0 \notin \mathcal{D}^\perp$$

# The first scalar invariant $\vartheta \in C^\infty(M)$

## Extension of $g|_{\mathcal{D}}$ depending on $(\mathcal{D}, g|_{\mathcal{D}})$

- extend  $g|_{\mathcal{D}}$  to a Riemannian metric  $\tilde{g}$  such that

$$Y_0 \perp_{\tilde{g}} \mathcal{D} \quad \text{and} \quad \tilde{g}(Y_0, Y_0) = 1$$

- angle  $\theta$  between  $Y_0$  and  $\mathcal{D}^\perp$  is given by

$$\cos \theta = \frac{|\tilde{g}(Y_0, Y_3)|}{\sqrt{\tilde{g}(Y_3, Y_3)}}, \quad 0 \leq \theta < \frac{\pi}{2}, \quad \mathcal{D}^\perp = \text{span}\{Y_3\}$$

- scalar invariant:  $\vartheta = \tan^2 \theta \geq 0$

$$Y_0 \in \mathcal{D}^\perp \iff \vartheta = 0$$

Curvature invariants  $\kappa, \chi_1, \chi_2 \in C^\infty(M)$

$$\kappa = \frac{1}{2} \text{Scal} \quad \chi_1 = \sqrt{-\det(g|_{\mathcal{D}}^{\#} \circ A_{sym}^b)} \quad \chi_2 = \sqrt{\det(g|_{\mathcal{D}}^{\#} \circ A_{skew}^b)}$$

- preserved by NH-isometries (i.e., **isometric invariants**)
- $\widehat{R} \equiv 0 \iff \kappa = 0$
- $\widehat{C} \equiv 0 \iff \chi_1 = \chi_2 = 0$

- 1 Nonholonomic Riemannian manifolds
  - Nonholonomic isometries
  - Curvature
- 2 Nonholonomic Riemannian structures in 3D
- 3 3D simply connected Lie groups
- 4 Classification of nonholonomic Riemannian structures in 3D
  - Case 1:  $\vartheta = 0$
  - Case 2:  $\vartheta > 0$
- 5 Flat nonholonomic Riemannian structures

# Bianchi–Behr classification of 3D Lie algebras

## Unimodular algebras and (simply connected) groups

Lie algebra	Lie group	Name	Class
$\mathbb{R}^3$	$\mathbb{R}^3$	Abelian	Abelian
$\mathfrak{h}_3$	$H_3$	Heisenberg	nilpotent
$\mathfrak{se}(1, 1)$	$SE(1, 1)$	semi-Euclidean	completely solvable
$\mathfrak{se}(2)$	$\widetilde{SE}(2)$	Euclidean	solvable
$\mathfrak{sl}(2, \mathbb{R})$	$\widetilde{SL}(2, \mathbb{R})$	special linear	semisimple
$\mathfrak{su}(2)$	$SU(2)$	special unitary	semisimple

## Non-unimodular (simply connected) groups

$\text{Aff}(\mathbb{R})_0 \times \mathbb{R}$ ,  $G_{3.2}$ ,  $G_{3.3}$ ,  $G_{3.4}^h$  ( $h > 0$ ,  $h \neq 1$ ),  $G_{3.5}^h$  ( $h > 0$ )



# Left-invariant distributions on 3D groups

## Killing form

$$\mathcal{K} : \mathfrak{g} \times \mathfrak{g} \rightarrow \mathbb{R}, \quad \mathcal{K}(U, V) = \text{tr}[U, [V, \cdot]]$$

- $\mathcal{K}$  is nondegenerate  $\iff \mathfrak{g}$  is semisimple

## Completely nonholonomic left-invariant distributions on 3D groups

- no such distributions on  $\mathbb{R}^3$  or  $G_{3,3}$

### Up to Lie group automorphism:

- exactly **one** distribution on  $H_3$ ,  $SE(1, 1)$ ,  $\widetilde{SE}(2)$ ,  $SU(2)$  and non-unimodular groups
- exactly **two** distributions on  $\widetilde{SL}(2, \mathbb{R})$ :

denote	$\widetilde{SL}(2, \mathbb{R})_{hyp}$	if $\mathcal{K}$ indefinite on $\mathcal{D}$
"	$\widetilde{SL}(2, \mathbb{R})_{ell}$	" " definite " "

- 1 Nonholonomic Riemannian manifolds
  - Nonholonomic isometries
  - Curvature
- 2 Nonholonomic Riemannian structures in 3D
- 3 3D simply connected Lie groups
- 4 Classification of nonholonomic Riemannian structures in 3D
  - Case 1:  $\vartheta = 0$
  - Case 2:  $\vartheta > 0$
- 5 Flat nonholonomic Riemannian structures

## Case 1: $\vartheta = 0$

- $\mathcal{D}^\perp = \text{span}\{Y_0\}$  determined by  $\mathcal{D}$ ,  $g|_{\mathcal{D}}$
- reduces to a **sub-Riemannian structure**  $(M, \mathcal{D}, g|_{\mathcal{D}})$
- invariant sub-Riemannian structures classified in

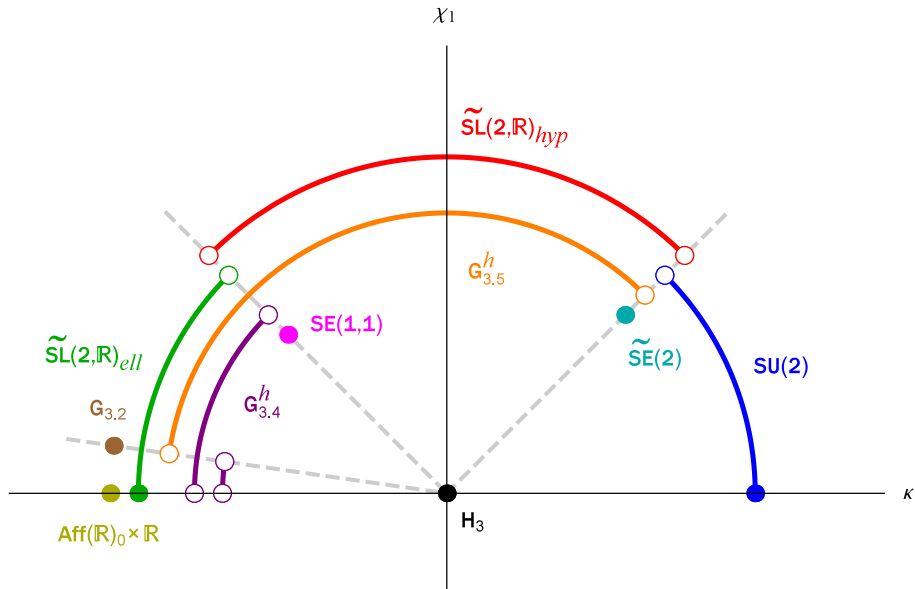
A. Agrachev and D. Barilari, Sub-Riemannian structures on 3D Lie groups,  
*J. Dyn. Control Syst.* **18**(2012), 21–44.

## Invariants

- $\{\kappa, \chi_1\}$  form a **complete set of invariants** for structures on unimodular groups
- structures on non-unimodular groups are further distinguished by discrete invariants
- can rescale structures so that

$$\kappa = \chi_1 = 0 \quad \text{or} \quad \kappa^2 + \chi_1^2 = 1$$

# Classification when $\vartheta = 0$



## Canonical frame $(X_0, X_1, X_2)$

$$X_0 = \mathcal{Q}(Y_0) \quad X_1 = \frac{\mathcal{P}(Y_0)}{\|\mathcal{P}(Y_0)\|} \quad X_2 \text{ unique unit vector s.t. } d\omega(X_1, X_2) = 1$$

- $\mathcal{D} = \text{span}\{X_1, X_2\}$ ,  $\mathcal{D}^\perp = \text{span}\{X_0\}$
- **canonical frame** (up to sign of  $X_0, X_1$ ) on  $M$

## Commutator relations (determine structure uniquely)

$$\begin{cases} [X_1, X_0] = c_{10}^1 X_1 + c_{10}^2 X_2 \\ [X_2, X_0] = c_{20}^0 X_0 + c_{20}^1 X_1 + c_{20}^2 X_2 \\ [X_2, X_1] = X_0 + c_{21}^1 X_1 + c_{21}^2 X_2 \end{cases} \quad c_{ij}^k \in C^\infty(M)$$

# Left-invariant structures

- canonical frame  $(X_0, X_1, X_2)$  is left invariant
- $\vartheta, \kappa, \chi_1, \chi_2$  and  $c_{ij}^k$  are constant

## NH-isometries preserve the Lie group structure

$(G, g, \mathcal{D})$  NH-isometric to  $(G', g', \mathcal{D}')$  w.r.t.  $\phi : G \rightarrow G'$   $\implies \phi = L_{\phi(\mathbf{1})} \circ \phi'$ , where  $\phi'$  is a Lie group isomorphism

- hence NH-isometries preserve the Killing form  $\mathcal{K}$

## Three new invariants $\varrho_0, \varrho_1, \varrho_2$

$$\varrho_i = -\frac{1}{2}\mathcal{K}(X_i, X_i), \quad i = 0, 1, 2$$

## Approach

- rescale frame so that  $\vartheta = 1$
- split into cases depending on structure constants
- determine group from commutator relations

Example:  $G$  is unimodular and  $c_{10}^1 = c_{10}^2 = 0$

$$[X_1, X_0] = 0 \quad [X_2, X_0] = -X_0 + c_{20}^1 X_1 \quad [X_2, X_1] = X_0 + X_1$$

- implies  $\mathcal{K}$  is degenerate (i.e.,  $G$  not semisimple)
  - (1)  $c_{20}^1 + 1 > 0 \implies$  compl. solvable    hence on  $SE(1, 1)$
  - (2)  $c_{20}^1 + 1 = 0 \implies$  nilpotent    "    "  $H_3$
  - (3)  $c_{20}^1 + 1 < 0 \implies$  solvable    "    "  $\widetilde{SE}(2)$
- for  $SE(1, 1)$ ,  $\widetilde{SE}(2)$ :  $c_{20}^1$  is a parameter (i.e., family of structures)

# Results (solvable groups)

$$H_3 \quad \begin{cases} [X_1, X_0] = 0 \\ [X_2, X_0] = -X_0 - X_1 \\ [X_2, X_1] = X_0 + X_1 \end{cases} \quad \begin{cases} \varrho_0 = 0 \\ \varrho_1 = 0 \\ \varrho_2 = 0 \end{cases}$$

$$SE(1, 1) \quad \begin{cases} [X_1, X_0] = -\sqrt{\alpha_1\alpha_2} X_1 - \alpha_1 X_2 \\ [X_2, X_0] = -X_0 - (1 - \alpha_2)X_1 + \sqrt{\alpha_1\alpha_2} X_2 \\ [X_2, X_1] = X_0 + X_1 \end{cases} \quad \begin{cases} \varrho_0 = -\alpha_1 \\ \varrho_1 = -\alpha_2 \\ \varrho_2 = -\alpha_2 \end{cases}$$

$$(\alpha_1, \alpha_2 \geq 0, \alpha_1^2 + \alpha_2^2 \neq 0)$$

$$\widetilde{SE}(2) \quad \begin{cases} [X_1, X_0] = -\sqrt{\alpha_1\alpha_2} X_1 + \alpha_1 X_2 \\ [X_2, X_0] = -X_0 - (1 + \alpha_2)X_1 + \sqrt{\alpha_1\alpha_2} X_2 \\ [X_2, X_1] = X_0 + X_1 \end{cases} \quad \begin{cases} \varrho_0 = \alpha_1 \\ \varrho_1 = \alpha_2 \\ \varrho_2 = \alpha_2 \end{cases}$$

$$(\alpha_1, \alpha_2 \geq 0, \alpha_1^2 + \alpha_2^2 \neq 0)$$



# Results (semisimple groups)

$$\text{SU}(2) \quad \begin{cases} [X_1, X_0] = -\delta X_0 + \alpha_1 X_2 \\ [X_2, X_0] = -X_0 - (1 + \alpha_2)X_1 + \delta X_2 \\ [X_2, X_1] = X_0 + X_1 \end{cases} \quad \begin{cases} \varrho_0 = \alpha_1(\alpha_2 + 1) - \delta^2 \\ \varrho_1 = \alpha_1 \\ \varrho_2 = \alpha_2 \end{cases}$$

$(\alpha_1, \alpha_2 > 0, \delta \geq 0, \delta^2 - \alpha_1\alpha_2 < 0)$

$$\widetilde{\text{SL}}(2, \mathbb{R})_{ell} \quad \begin{cases} [X_1, X_0] = -\delta X_1 - \alpha_1 X_2 \\ [X_2, X_0] = -X_0 - (1 - \alpha_2)X_1 + \delta X_2 \\ [X_2, X_1] = X_0 + X_1 \end{cases} \quad \begin{cases} \varrho_0 = \alpha_1(\alpha_2 - 1) - \delta^2 \\ \varrho_1 = -\alpha_1 \\ \varrho_2 = -\alpha_2 \end{cases}$$

$(\alpha_1, \alpha_2 > 0, \delta \geq 0, \delta^2 - \alpha_1\alpha_2 < 0)$

$$\widetilde{\text{SL}}(2, \mathbb{R})_{hyp} \quad \begin{cases} [X_1, X_0] = -\delta X_1 - \gamma_1 X_2 \\ [X_2, X_0] = -X_0 - (1 - \gamma_2)X_1 + \delta X_2 \\ [X_2, X_1] = X_0 + X_1 \end{cases} \quad \begin{cases} \varrho_0 = \gamma_1(\gamma_2 - 1) - \delta^2 \\ \varrho_1 = -\gamma_1 \\ \varrho_2 = -\gamma_2 \end{cases}$$

$(\delta \geq 0, \gamma_1, \gamma_2 \in \mathbb{R}, \delta^2 - \gamma_1\gamma_2 > 0)$

## Structures on unimodular groups

- $\{\vartheta, \varrho_0, \varrho_1, \varrho_2\}$  form a **complete set of invariants**
- $\{\vartheta, \kappa, \chi_1\}$  also suffice for  $H_3$ ,  $SE(1, 1)$ ,  $\widetilde{SE}(2)$
- $\chi_2 = 0$

## Structures on 3D non-unimodular groups

On a fixed non-unimodular Lie group (except for  $G_{3,5}^1$ ), there exist **at most two** non-NH-isometric structures with the same invariants  $\vartheta, \varrho_0, \varrho_1, \varrho_2$

- exception  $G_{3,5}^1$ : infinitely many ( $\varrho_0 = \varrho_1 = \varrho_2 = 0$ )
- use  $\kappa, \chi_1$  or  $\chi_2$  to form complete set of invariants

- 1 Nonholonomic Riemannian manifolds
  - Nonholonomic isometries
  - Curvature
- 2 Nonholonomic Riemannian structures in 3D
- 3 3D simply connected Lie groups
- 4 Classification of nonholonomic Riemannian structures in 3D
  - Case 1:  $\vartheta = 0$
  - Case 2:  $\vartheta > 0$
- 5 Flat nonholonomic Riemannian structures

# Flat nonholonomic Riemannian structures

## Definition

$(M, g, \mathcal{D})$  is **flat** if the parallel transport induced by  $\nabla$  does not depend on the path taken

## Characterisations

- $(M, g, \mathcal{D})$  is flat  $\iff$  there exists a **parallel frame** for  $\mathcal{D}$ , i.e., an o.n. frame  $(X_a)$  for  $\mathcal{D}$  s.t.  $\nabla X_a \equiv 0$
- an o.n. frame  $(X_a)$  for  $\mathcal{D}$  is parallel  $\iff \mathcal{P}([X_a, X_b]) = 0$  for every  $a, b = 1, \dots, r$

## In Riemannian geometry

$(M, g)$  is flat  $\iff$  Riemannian curvature tensor  $R \equiv 0$

**Vanishing of Schouten tensor does not characterise flatness of  $(M, g, \mathcal{D})$**

# Wagner's approach

## Flag of $\mathcal{D}$

$$\mathcal{D} = \mathcal{D}^1 \subsetneq \mathcal{D}^2 \subsetneq \dots \subsetneq \mathcal{D}^N = TM$$

- $\mathcal{D}^{i+1} = \mathcal{D}^i + [\mathcal{D}^i, \mathcal{D}^i]$ ,  $i \geq 1$

## Approach

For each  $i = 1, \dots, N$ , define a new connection

$$\nabla^i : \Gamma(\mathcal{D}^i) \times \Gamma(\mathcal{D}) \rightarrow \Gamma(\mathcal{D})$$

such that

- $\nabla^1 = \nabla$  and  $\nabla^{i+1}|_{\Gamma(\mathcal{D}^i) \times \Gamma(\mathcal{D})} = \nabla^i$
- $\nabla^i X \equiv 0 \iff \nabla^{i+1} X \equiv 0$

- $\nabla^N$  is a **vector bundle connection** with curvature  $K^N$
- $(M, g, \mathcal{D})$  is flat  $\iff K^N \equiv 0$

# The Wagner curvature tensor

## Assumption

$$\mathcal{D}^{i+1} = \mathcal{D}^i \oplus \mathcal{E}^i, \quad \text{for each } i = 1, \dots, N-1$$

- **not preserved under NH-isometry** (unless  $N = 2$ )
- projectors  $\mathcal{P}_i : TM \rightarrow \mathcal{D}^i$ ,  $\mathcal{Q}_i : TM \rightarrow \mathcal{E}^i$

## Construction

If  $Z = X + A \in \Gamma(\mathcal{D}^{i+1}) = \Gamma(\mathcal{D}^i \oplus \mathcal{E}^i)$ , then

$$\nabla_Z^{i+1} U = \nabla_X^i U + K^i(\Theta_i(A))U + \mathcal{P}([A, U])$$

Here

- $\Theta_i = \Delta_i|_{(\ker \Delta_i)^\perp}^{-1}$  and  $\Delta_i : \wedge^2 \mathcal{D}^i \rightarrow \mathcal{E}^i$ ,  $X \wedge Y \mapsto \mathcal{Q}_i([X, Y])$
- $K^i(X \wedge Y)U = [\nabla_X^i, \nabla_Y^i]U - \nabla_{\mathcal{P}_i([X, Y])}^i U - \mathcal{P}([\mathcal{Q}_i([X, Y]), U])$

$K^N$  is called the **Wagner curvature tensor**